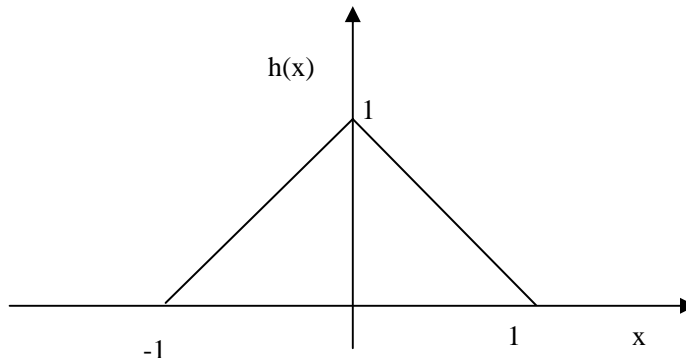


SD575 Digital Image Processing – Midterm Examination
October 18, 2007 8:45am – 10:15am
Prof. D. A. Clausi

1. Consider an LSI system with impulse response $h(x)$:



- (a) Determine the response $g(x)$ of the system to a unit step. What is the impact (qualitatively) on the image when $h(x)$ is applied?
- (b) Is the system $h(x)$ causal? Explain. Is the system $h(x)$ memoryless? Explain.
- (c) Find the frequency response $H_1(u)$ that compensates for $h(x)$.
- (d) For low frequencies, $H_1(u)$ can be approximated with the following form of the frequency response:

$$\mathbf{H_1(u) = \frac{1}{1 - c^2 u^2}}$$

Find c . Hint: Use the Taylor series expansion $\cos x \sim 1 - 0.5 x^2$

- (e) If $f(x)$ and $g(x)$ are the input and output of the system of $H(u)$, what is the differential equation relating $f(x)$ and $g(x)$?

2. Consider the following probability density function that represents the probability of occurrence for grey levels in an image:

$$p_f(r) = k e^{-ar} \quad 0 \leq r \leq 1$$

- (a) Derive k to ensure that $p_f(r)$ is a true pdf.
- (b) What point operation maps this pdf to a uniform distribution? How is the local contrast affected in both light and dark regions of the input image?

Now consider the discrete histogram $\mathbf{H(k) = 128(0.5)^k}$, $\mathbf{0 \leq k \leq 7}$

- (c) Devise a histogram equalization solution, provide the transformation, and sketch your resulting histogram.
- (d) Is histogram equalization in general a linear system? an invertible system? a memoryless system? For each case, explain your answer.

$$H_{inv}(u) = \left(\frac{\pi u}{\sin \pi u} \right)^2$$

$$(d) \quad H_{inv}(u) = \frac{\pi^2 u^2}{1 - \cos^2 \pi u} \approx \frac{\pi^2 u^2}{1 - (1 - \frac{1}{2} \pi^2 u^2)^2}$$

$$= \frac{\pi^2 u^2}{\pi^2 u^2 - \frac{1}{4} \pi^4 u^4}$$

$$\therefore \text{for small } u, H_{inv}(u) \approx \frac{1}{1 - \frac{1}{4} \pi^2 u^2} \text{ and } c = \frac{\pi}{2}$$

$$(e) \quad H(u) = \frac{G(u)}{F(u)} = 1 - \frac{1}{4} \pi^2 u^2 \quad (\text{for low frequencies})$$

$$\therefore g(x) = f(x) + \frac{1}{10} f''(x)$$

Brute Force (Q 9(c)) M-3

$$H(u) = \int_{-\infty}^{\infty} h(x) e^{-j2\pi ux} dx = \int_{-1}^0 (x+1) e^{-j2\pi ux} dx + \int_0^1 (-x+1) e^{-j2\pi ux} dx$$

$$= \int_{-1}^0 x e^{-j2\pi ux} dx + \int_{-1}^0 e^{-j2\pi ux} dx + \int_0^1 x e^{-j2\pi ux} dx + \int_0^1 e^{-j2\pi ux} dx$$

(A) (B) (C) (D)

(A) $\int_{-1}^0 x e^{-j2\pi ux} dx$

$u = x \quad v = \frac{e^{-j2\pi ux}}{-j2\pi u}$
 $du = dx \quad dv = e^{-j2\pi ux}$

$$= \frac{x e^{-j2\pi ux}}{-j2\pi u} \Big|_{-1}^0 + \int_{-1}^0 \frac{e^{-j2\pi ux}}{j2\pi u} dx$$

$$\int u dv = uv - \int v du$$

$$= \frac{-e^{-j2\pi u}}{j2\pi u} + \frac{e^{-j2\pi u}}{4\pi^2 u^2} \Big|_{-1}^0$$

$$= \frac{-e^{+j2\pi u}}{j2\pi u} + \frac{1}{4\pi^2 u^2} - \frac{e^{j2\pi u}}{4\pi^2 u^2}$$

(B) $\int_{-1}^0 e^{-j2\pi ux} dx = \frac{e^{+j2\pi u}}{j2\pi u} - \frac{1}{j2\pi u}$

(C) $-\int_0^1 x e^{-j2\pi ux} dx = - \left[\frac{x e^{-j2\pi ux}}{-j2\pi u} + \frac{e^{-j2\pi ux}}{4\pi^2 u^2} \Big|_0^1 \right]$

$$= \frac{e^{-j2\pi u}}{j2\pi u} - \frac{e^{-j2\pi u}}{4\pi^2 u^2} + \frac{1}{4\pi^2 u^2}$$

(D) $\int_0^1 e^{-j2\pi ux} dx = \frac{1}{j2\pi u} - \frac{e^{-j2\pi u}}{j2\pi u}$

$$(A) + (B) + (C) + (D) = \frac{2}{4\pi^2 u^2} - \frac{e^{j2\pi u}}{4\pi^2 u^2} - \frac{e^{-j2\pi u}}{4\pi^2 u^2}$$

$$= \left(\frac{e^{j2\pi u} - e^{-j2\pi u}}{j2\pi u} \right)^2$$

$$= \left(\frac{\sin 2\pi u}{\pi u} \right)^2$$

$$\therefore \text{z. (a)} \quad k \int_0^1 e^{-ar} dr = 1$$

$$k \left[\frac{e^{-ar}}{-a} \right]_0^1 = 1$$

$$k \left[\frac{e^{-a} - 1}{-a} \right] = 1 \Rightarrow k = \frac{a}{1 - e^{-a}}$$

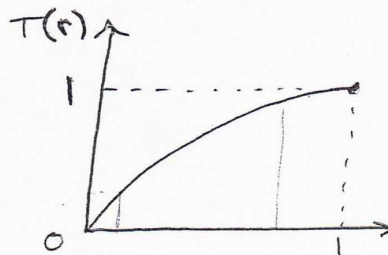
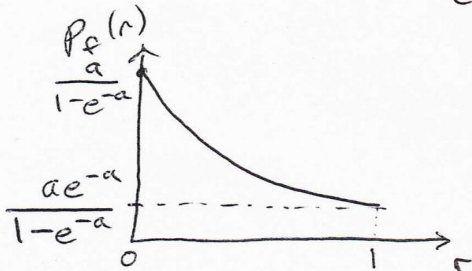
$$\therefore p_r(r) = \frac{a}{1 - e^{-a}} e^{-ar} \quad 0 \leq r \leq 1$$

$$(b) \quad T(r) = \int_0^r \frac{a}{1 - e^{-a}} e^{-ax} dx \quad 0 \leq r \leq 1$$

$$= \frac{a}{1 - e^{-a}} \left[\frac{e^{-ax}}{-a} \right]_0^r$$

$$= \frac{a}{1 - e^{-a}} \left[\frac{e^{-ar} - 1}{-a} \right]$$

$$= \frac{1 - e^{-ar}}{1 - e^{-a}}, \quad 0 \leq r \leq 1$$



~~stretch~~

slope > 1

~~compress~~

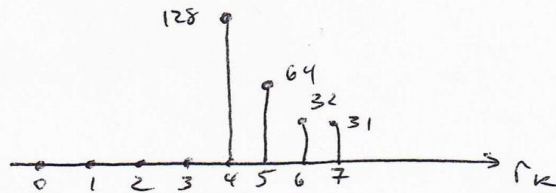
slope < 1

$$128 \sum_{k=0}^7 (1/2)^k = 128 \left[\frac{1 - (1/2)^8}{1 - 1/2} \right] = 256 \left(\frac{256 - 1}{256} \right) \approx 255 \quad M=5$$

(c) $H(k) = 128 (1/2)^k \quad 0 \leq k \leq 7$

r_k	0	1	2	3	4	5	6	7
$P_r(r_k)$	$\frac{128}{255}$	$\frac{64}{255}$	$\frac{32}{255}$	$\frac{16}{255}$	$\frac{8}{255}$	$\frac{4}{255}$	$\frac{2}{255}$	$\frac{1}{255}$
cdf	$\frac{128}{255}$	$\frac{192}{255}$	$\frac{224}{255}$	$\frac{240}{255}$	$\frac{248}{255}$	$\frac{252}{255}$	$\frac{254}{255}$	$\frac{255}{255}$
$(L-1)$ cdf	$\frac{128}{255}$	$\frac{896}{255}$	$\frac{1344}{255}$	$\frac{1568}{255}$	$\frac{1680}{255}$	$\frac{1736}{255}$	$\frac{1764}{255}$	$\frac{1778}{255}$
round(s_k)	4	5	6	7	7	7	7	7
output	0	0	0	0	128	64	32	31

$$s_k = T(r_k) = (L-1) \sum_{j=0}^k P_r(r_j)$$



(d) linear \Rightarrow NO

- generally mapping $f(x)$ is non-linear

invertible \Rightarrow YES, if continuous

NO, if discrete due to bin filling

memoryless \Rightarrow YES, point operation