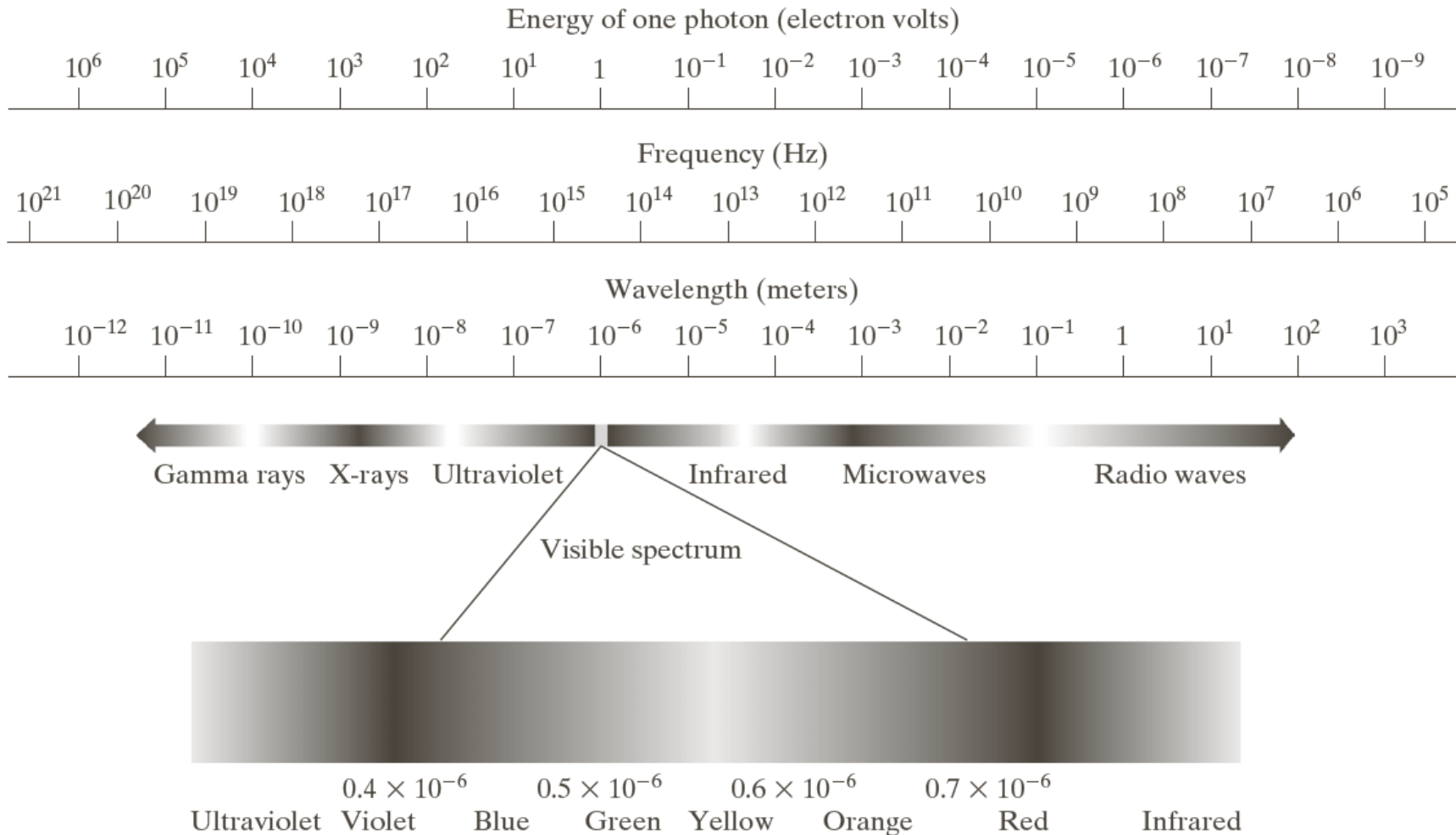


# **SYDE 575: Introduction to Image Processing**

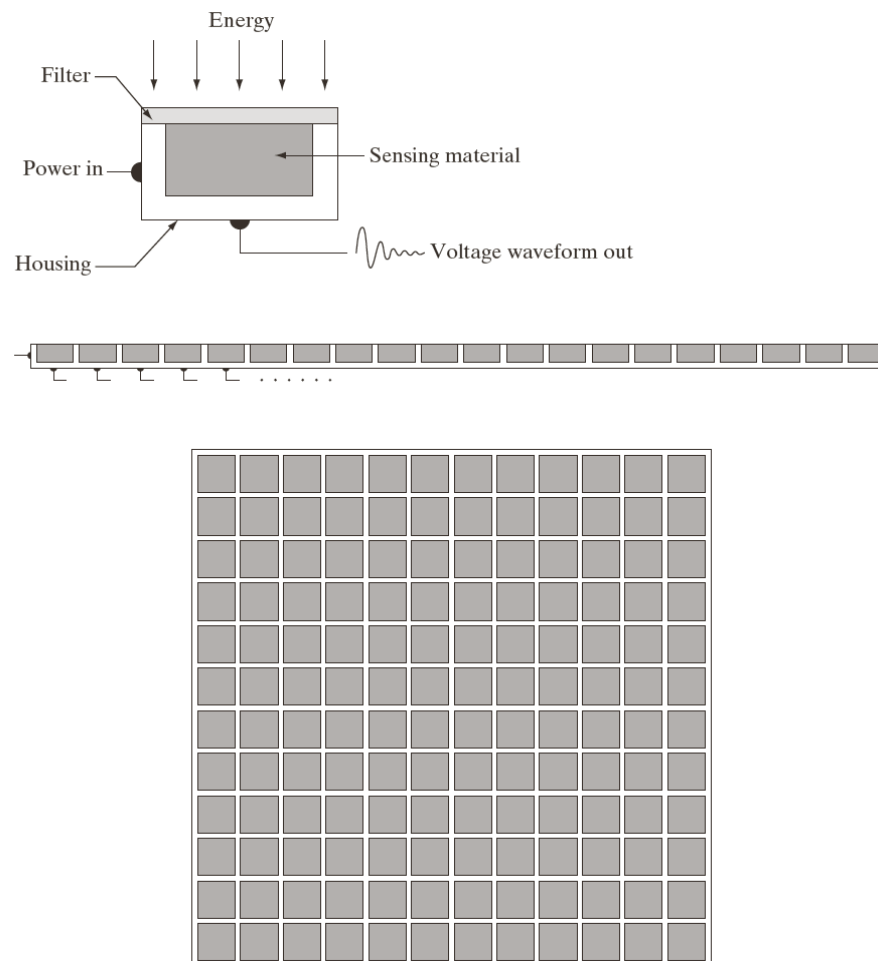
Digital Image Processing Fundamentals

# Electromagnetic Spectrum



Source: Gonzalez and Woods

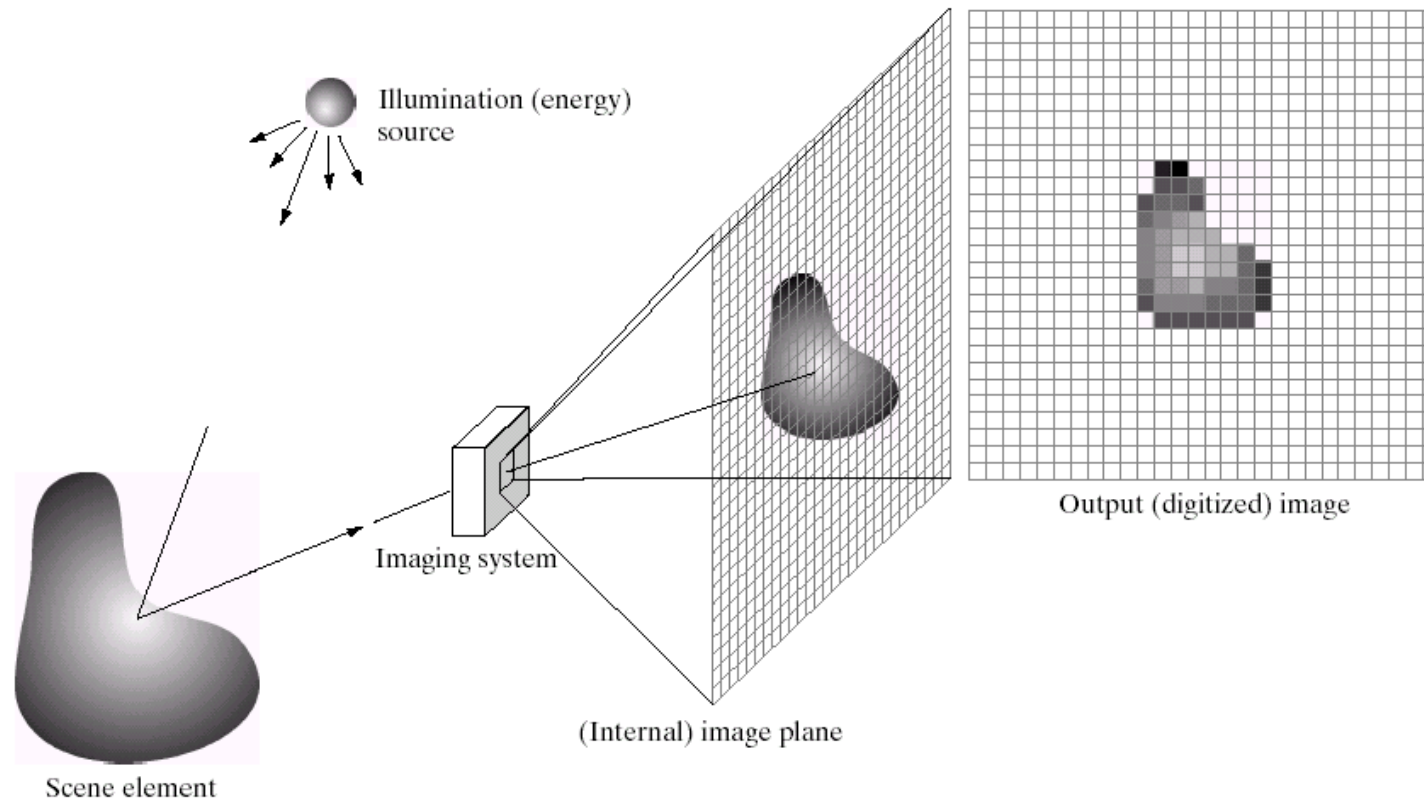
# Image Sensing



a  
b  
c

**FIGURE 2.12**  
(a) Single imaging sensor.  
(b) Line sensor.  
(c) Array sensor.

# Digital Image Acquisition Example



a b c d e

**FIGURE 2.15** An example of the digital image acquisition process. (a) Energy (“illumination”) source. (b) An element of a scene. (c) Imaging system. (d) Projection of the scene onto the image plane. (e) Digitized image.

# Simple Image Formation Model

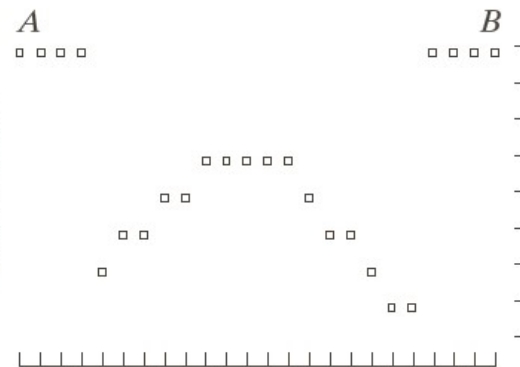
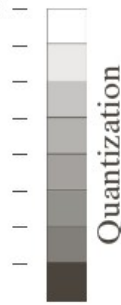
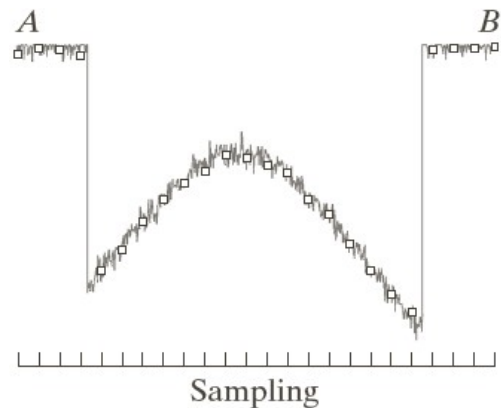
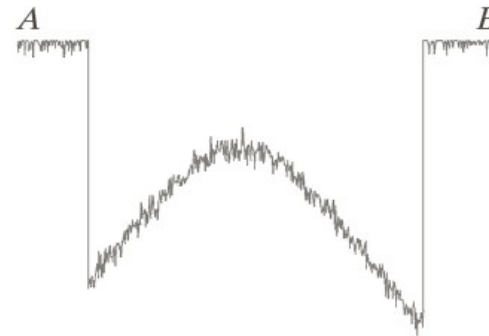
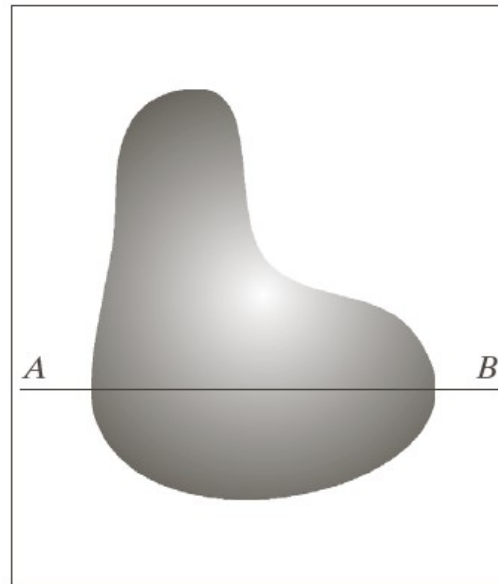
- Image may be characterized by:
  - Amount of source illumination incident on scene
  - Amount of illumination reflected by objects in scene  
( $r=0$  for total absorption, and  $r=1$  for total reflectance)

$$f(x, y) = i(x, y)r(x, y)$$

$$0 < i(x, y) < \infty$$

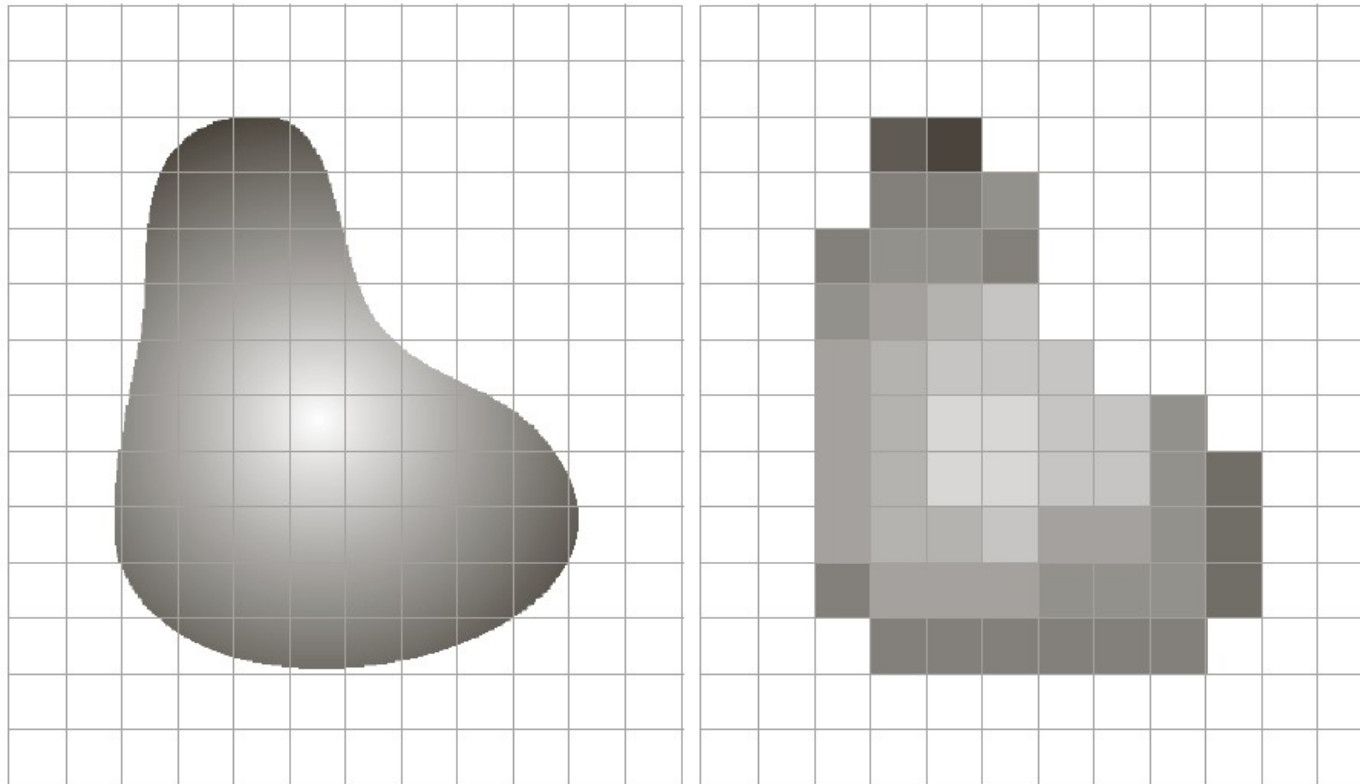
$$0 < r(x, y) < 1$$

# Image Sampling and Quantization



Source: Gonzalez and Woods

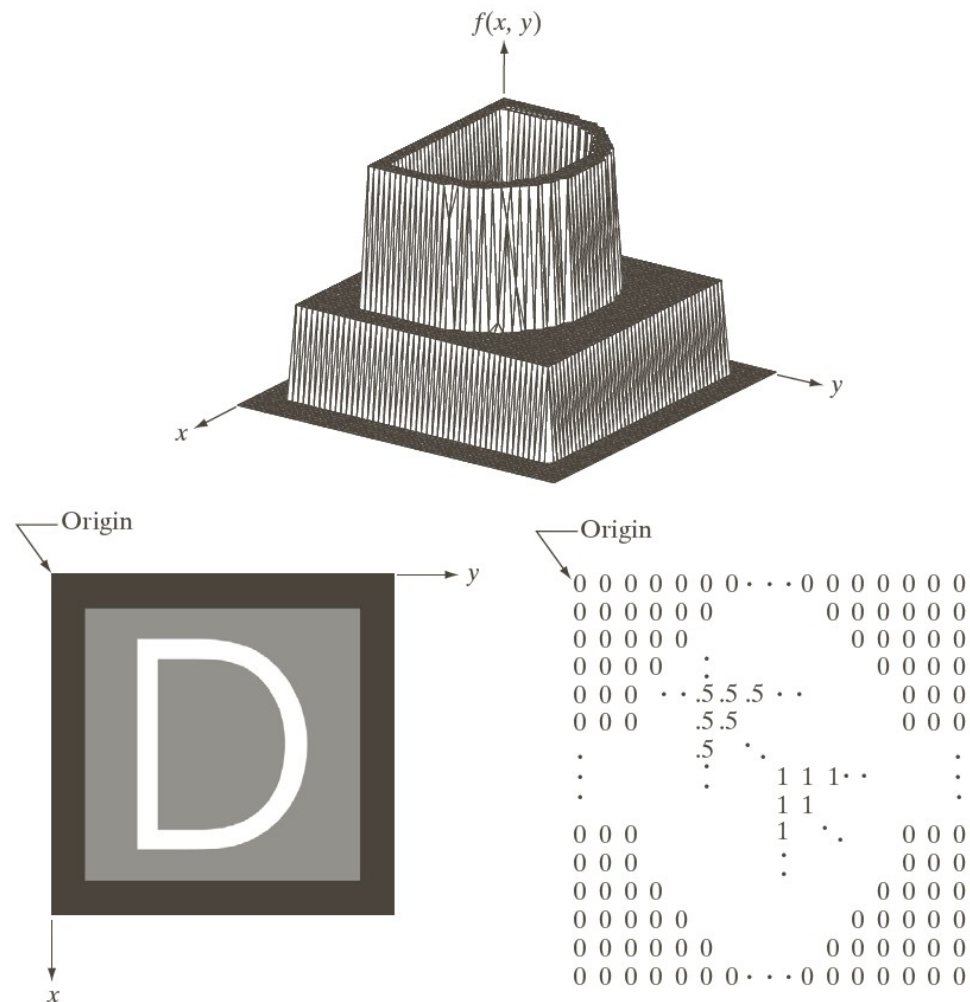
# Example



a b

**FIGURE 2.17** (a) Continuous image projected onto a sensor array. (b) Result of image sampling and quantization.

# Digital Image Representation



Source: Gonzalez and Woods



# Spatial Resolution



a b  
c d

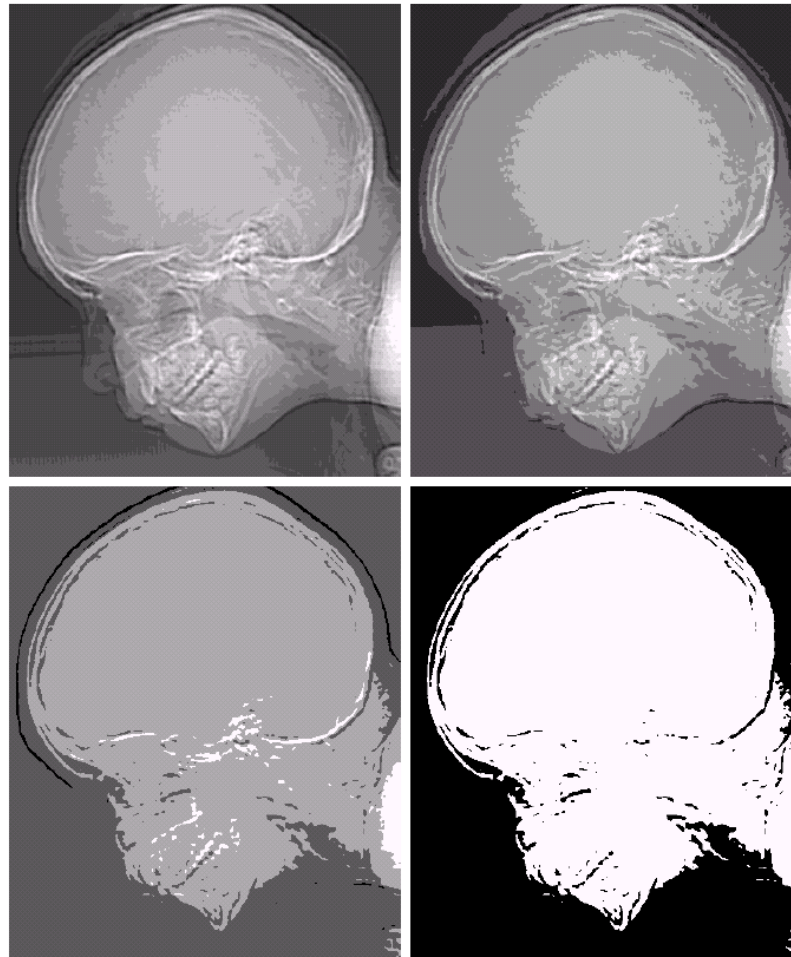
**FIGURE 2.20** Typical effects of reducing spatial resolution. Images shown at: (a) 1250 dpi, (b) 300 dpi, (c) 150 dpi, and (d) 72 dpi. The thin black borders were added for clarity. They are not part of the data.

Source: Gonzalez and Woods

# Gray-level Resolution

e f  
g h

**FIGURE 2.21**  
*(Continued)*  
(e)–(h) Image displayed in 16, 8, 4, and 2 gray levels. (Original courtesy of Dr. David R. Pickens, Department of Radiology & Radiological Sciences, Vanderbilt University Medical Center.)



Source: Gonzalez and Woods

# Digital Zooming

- Nearest neighbor interpolation
  - Look for closest pixel in original image
  - Fast but causes undesirable checkerboard effect
- Bilinear interpolation
  - Determines pixel value based on four nearest neighbors
    - Do linear interpolation in x direction
    - Do linear interpolation in y direction based on results of interpolation from x direction
  - Does not suffer from checkerboard effect but can result in a blurred appearance

# Digital Zooming

- Bicubic Interpolation
  - Determines pixel value based on sixteen nearest neighbors
    - Do cubic spline interpolation in x direction
    - Do cubic spline interpolation in y direction based on results of interpolation from x direction
  - Does not suffer from checkerboard effect like nearest neighbor interpolation and preserves fine details better than bilinear interpolation

# Zooming Results



Nearest Neighbor



Bilinear Interpolation



Bicubic Interpolation

Source: Gonzalez and Woods

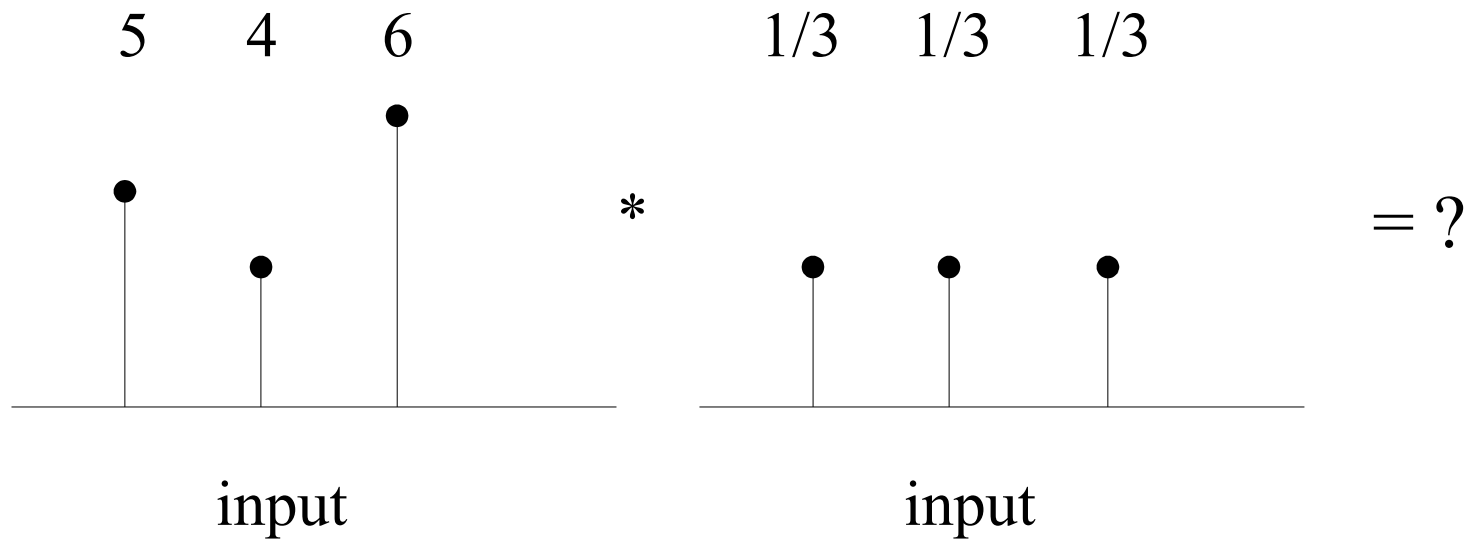
# Discrete Convolution

$$g[n] = f[n] * h[n] = \sum_{k=-\infty}^{\infty} f[k] \cdot h[n - k]$$

↑                    ↑                    ↑

output            input            impulse  
function

# Discrete Convolution Example



# Discrete Convolution in 2D

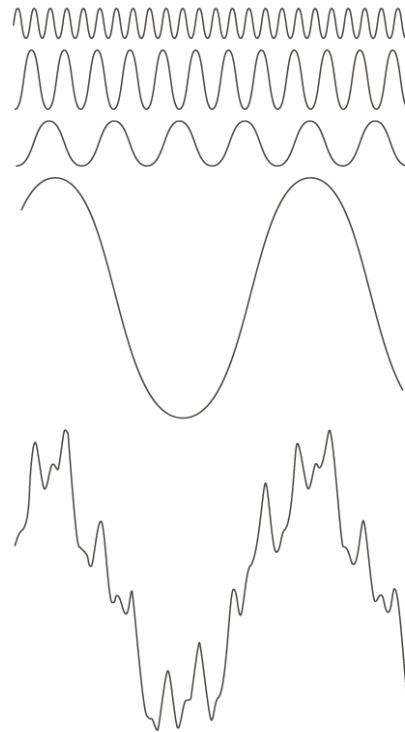
$$g[m,n] = f[m,n] * h[m,n] = \sum_{j=-\infty}^{\infty} \sum_{i=-\infty}^{\infty} f[i,j] \cdot h[m-i, n-j]$$

output          input          impulse  
function



# Discrete Fourier Transform

- A signal can be expressed as a weighted sum of sines and cosines



**FIGURE 4.1** The function at the bottom is the sum of the four functions above it. Fourier's idea in 1807 that periodic functions could be represented as a weighted sum of sines and cosines was met with skepticism.

# Discrete Fourier Transform

- Euler's formula

$$e^{j\theta} = \cos\theta + j \sin\theta$$

- Based on this, summation of sines and cosines can be expressed

$$e^{-j2\pi ux/M} = \cos(2\pi ux/M) - j \sin(2\pi ux/M)$$

↑  
cosines

↑  
sines

# Discrete Fourier Transform

$$F(u) = \frac{1}{M} \sum_{x=0}^{M-1} f(x) e^{-j2\pi ux/M} \text{ for } u=0,1,2,\dots,M-1$$

↑  
output

↑  
input

↑  
sinusoids

$$f(x) = \sum_{u=0}^{M-1} F(u) e^{j2\pi ux/M} \text{ for } x=0,1,2,\dots,M-1$$

# Discrete Fourier Transform in 2D

- For an MxN image

$$F(u, v) = \frac{1}{MN} \sum_{x=0}^{M-1} \sum_{y=0}^{N-1} f(x, y) e^{-j2\pi (ux/M + vy/N)}$$

↑  
output

↑  
input

↑  
sinusoids

$$f(x, y) = \sum_{u=0}^{M-1} \sum_{v=0}^{N-1} F(u, v) e^{j2\pi (ux/M + vy/N)}$$

# Fourier Analysis: Spectra

$$|F(u, v)| = \left[ R^2(u, v) + I^2(u, v) \right]^{1/2}$$

$$R = \operatorname{Re}(F(u, v)), \quad I = \operatorname{Im}(F(u, v))$$

- Power Spectrum

$$P(u, v) = |F(u, v)|^2$$

# Fourier Spectra Characteristics of Images

- Most energy reside in low frequency components
  - Implies that the original image can be reconstructed with good approximation with the low frequency components
- Low frequency components correspond to coarse details
  - e.g., DC component represents average color of an image
- High frequency components correspond to fine details
  - e.g., edges, noise

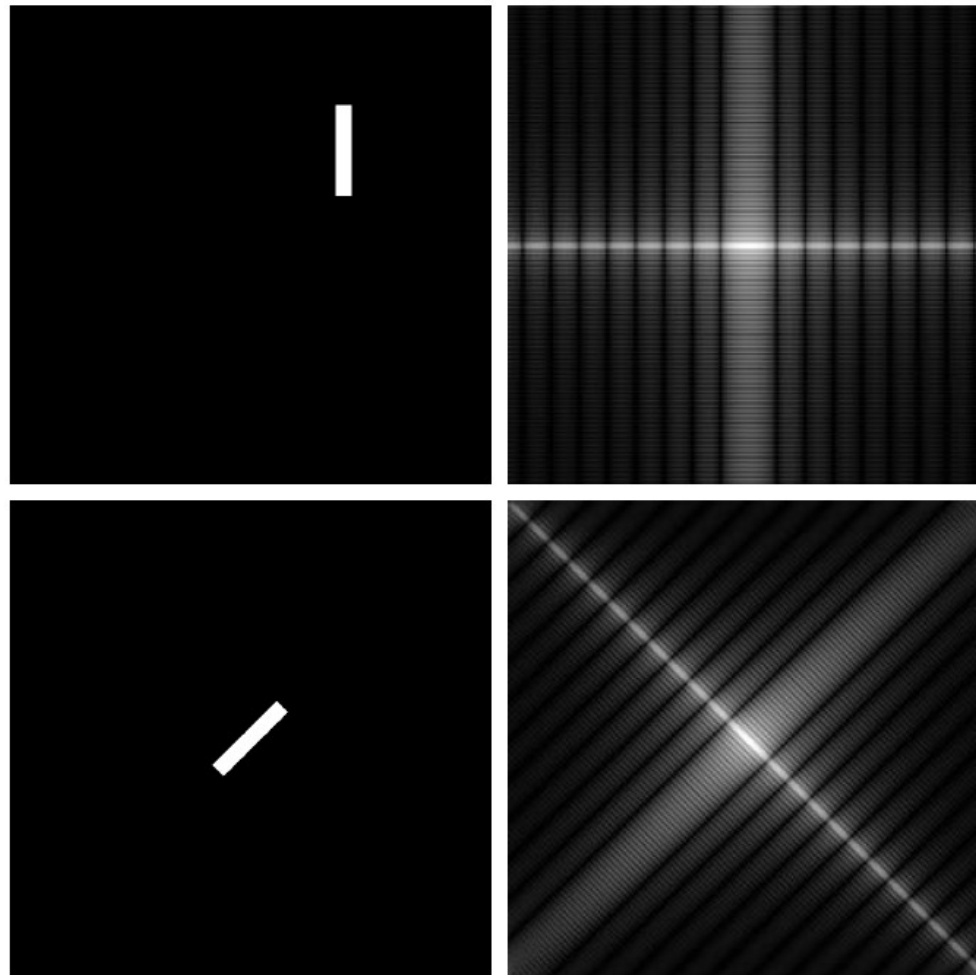
# Fourier Analysis: Spectra

- In image coordinates, origin (0,0) refers to top-left corner
- Results in spectra being centered at corner
- Common practice to multiply input image by  $(-1)^{x+y}$ 
  - Why?

$$\mathcal{F} \left[ f(x, y)(-1)^{x+y} \right] = F(u - M / 2, v - N / 2)$$

- Brings original of spectra to center of image

# Fourier Spectra Example



a	b
c	d

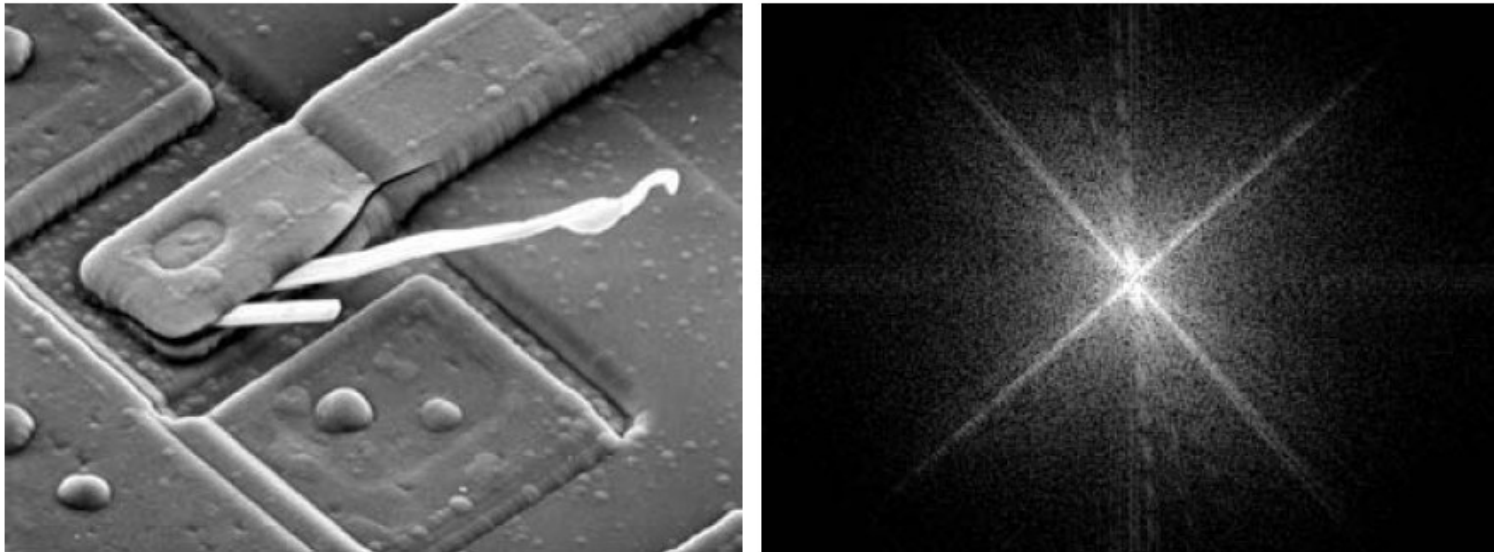
**FIGURE 4.25**

(a) The rectangle in Fig. 4.24(a) translated, and (b) the corresponding spectrum.

(c) Rotated rectangle, and (d) the corresponding spectrum. The spectrum corresponding to the translated rectangle is identical to the spectrum corresponding to the original image in Fig. 4.24(a).



# Fourier Spectra Example



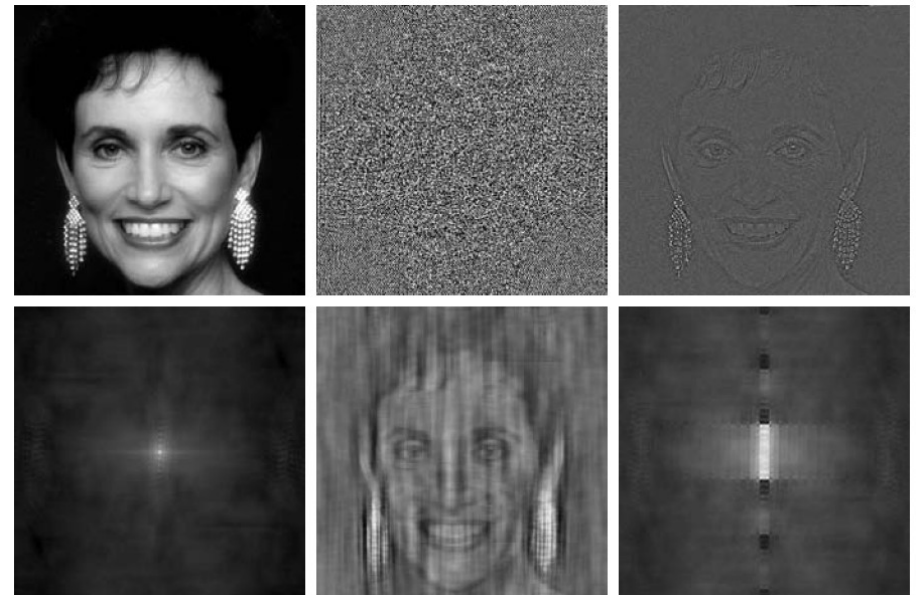
a b

**FIGURE 4.29** (a) SEM image of a damaged integrated circuit. (b) Fourier spectrum of (a). (Original image courtesy of Dr. J. M. Hudak, Brockhouse Institute for Materials Research, McMaster University, Hamilton, Ontario, Canada.)

# Fourier Analysis: Phase

- Characterizes structural information within an image

$$\phi(u, v) = \tan^{-1} \left[ \frac{I(u, v)}{R(u, v)} \right]$$



a b c  
d e f

**FIGURE 4.27** (a) Woman. (b) Phase angle. (c) Woman reconstructed using only the phase angle. (d) Woman reconstructed using only the spectrum. (e) Reconstruction using the phase angle corresponding to the woman and the spectrum corresponding to the rectangle in Fig. 4.24(a). (f) Reconstruction using the phase of the rectangle and the spectrum of the woman.

Source: Gonzalez and Woods

# Transfer Function

$$G(u, v) = F(u, v)H(u, v)$$

↑  
output

↑  
input

↑  
transfer  
function

# Image Quality Measures

$$MSE = \frac{1}{mn} \sum_{i=0}^{m-1} \sum_{j=0}^{n-1} \|f(i, j) - g(i, j)\|^2$$

$$PSNR = 10 \log_{10} \left( \frac{MAX_f^2}{MSE} \right) = 20 \log_{10} \left( \frac{MAX_f}{\sqrt{MSE}} \right)$$